AMIRHOSEIN TOOSI

Computer Vision/Deep Learning Eng.

13 November 1984

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About me —

Computer Vision & Deep learning specialist at Abinsula s.r.l. Working on Embedded Deep Learning-based Computer Vision solutions. Former post-doc researcher at Computer Graphics and Vision Group, department of Computer and Control Engineering (DAUIN) Polytechnic University of Turin. Worked on Deep Learning based multi-view 3D human pose estimation and tracking for sport events. He received his PhD in Computer and Control Engineering from Polytechnic University of Turin, and his Master's in Mechatronics Engineering from Qazvin Azad University. He worked on software-based Biometrics liveness detection systems as for his PhD's research project. For his Master's thesis project he developed a Haptic VR Simulator for root canal treatments training. Previously, he received his B.s. in Computer Software Eng. from Tehran Azad University. Skills including:

- Machine Learning, Deep Learning, Computer Vision, Image processing, etc.
- Physics-based Haptic VR Simulators for surgical procedures training.
 - Robotics Programming (ROS framework)
- Strong background in developing multidisciplinary engineering software solutions.

Skills —

Python

Caffe/Tensorflow/Keras/PyTorch

OpenCV

Matlab scripting language

OpenGL/OpenHaptics/WebGL/is

C/C++

ROS

ETFX

Education

2017-19	Post-doc. Computer and Control Engineering Politecnico di Torino	Turin, Italy
2014-17	Ph.D. Computer and Control Engineering Politecnico di Torino	Turin, Italy
2010-13	M.Sc. Mechatronics Engineering Qazvin Azad University (QIAU)	Qazvin, Iran
2003-08	B.Sc. Computer Software Engineering Tehran Azad University	Tehran, Iran

Experience

since 2019	Computer Vision & Deep learning specialist	Abinsula s.r.l
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- VIGNAL project: Pedestrian detection and collision avoidance for forklifts.
- EasyRain project: On-board Driver Distraction Inhibitor system.
- Topcon/WEEO project: Agriculture vehicles monitoring smartphone app.

2017-19 Postdoc Researcher Politecnico di Torino

- Multi-view 3D human pose estimation and tracking in sports events

2014-17 PhD Candidate / Researcher Politecnico di Torino

Feature Fusion for biometrics spoof detection

2011-14 Robotic systems software developer AFACO Group

CCTV Sewer Inspection Robotic Systems Software developer.

2013-14 Research assistant Shahid Rajaee University

- Haptic VR simulation of surgical stitching of soft tissue.
- Haptic VR simulation of Cataract surgery.

2012-13 Researcher/Software Developer Mechatronics Research Laboratory

- Member of Service Robots team (@home league).
- Object Detection, grasping and Trajectory planning for 6-DOF robotic arm.

Tehran Municipality

2012-13 Robotics coach/supervisor

- Head of Tehran Municipality Robotics Association.
- Coach and mentor of student robotics teams.
- Award Winner of several domestic and international robotics competitions.

Publications

2018	A. Toosi, A. Bottino, S. Cumani, "Assessing Transfer Learning on Convolutional
	Neural Networks for patch–based Fingerprint Liveness Detection", $Studies\ in$
	Computational Intelligence, Springer.

2017 A. Toosi, A. Bottino, S. Cumani, "Convolutional Neural Network Patch-based Voting for Fingerprint Liveness Detection", 9th International Joint Conference on Computational Intelligence.

2017 A. Toosi, A. Bottino, S. Cumani, P. Negri, P. Sottile, "Feature Fusion for Finger-print Liveness Detection: a Comparative Study", *IEEE Access*.

2016	A. Bottino, A. Martina, F, Strada, A. Toosi, "GAINE - A Portable Framework for
	the Development of Edutainment Applications Based on Multitouch and Tangi-
	ble Interaction", Journal of Entertainment Computing Elsevier

2015	$A.\ Toosi,\ S.\ Cumani,\ A.\ Bottino,\ "On\ Multiview\ Analysis\ of\ Fingerprint\ Images\ for$
	the Development of Spoofing Detection Methods" , $\it 14th Iberoamerican Congress$
	on Pattern Recognition.

2015	A. Bottino, A. Martina, A. Toosi, "GAINE - tanGible Augmented Interaction for
	Edutatement", INTETAIN 2015.

2014	A. Toosi, M. Arbabtafti, B. Richardson, "Virtual Reality Haptic Simulation of
	Root Canal Therapy", Journal of Applied Mechanics and Materials.